

# The AE9/AP9 Radiation Specification Development

15 September 2009

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Chestnut Hill, MA

Prepared for:

National Reconnaissance Office  
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Chantilly, VA 20151-1715

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Authorized by: National Systems Group

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Approved by:



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J. H. CLEMMONS, Principal Director  
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Research & Technology  
Imaging Programs Division  
National Systems Group



# The AE9/AP9 Radiation Specification Development

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Space Science Department, The Aerospace Corporation

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Stu Huston, AFRL/RVBX (Boston College)

Space Sciences Applications Lab Seminar  
July 28<sup>th</sup>, 2009

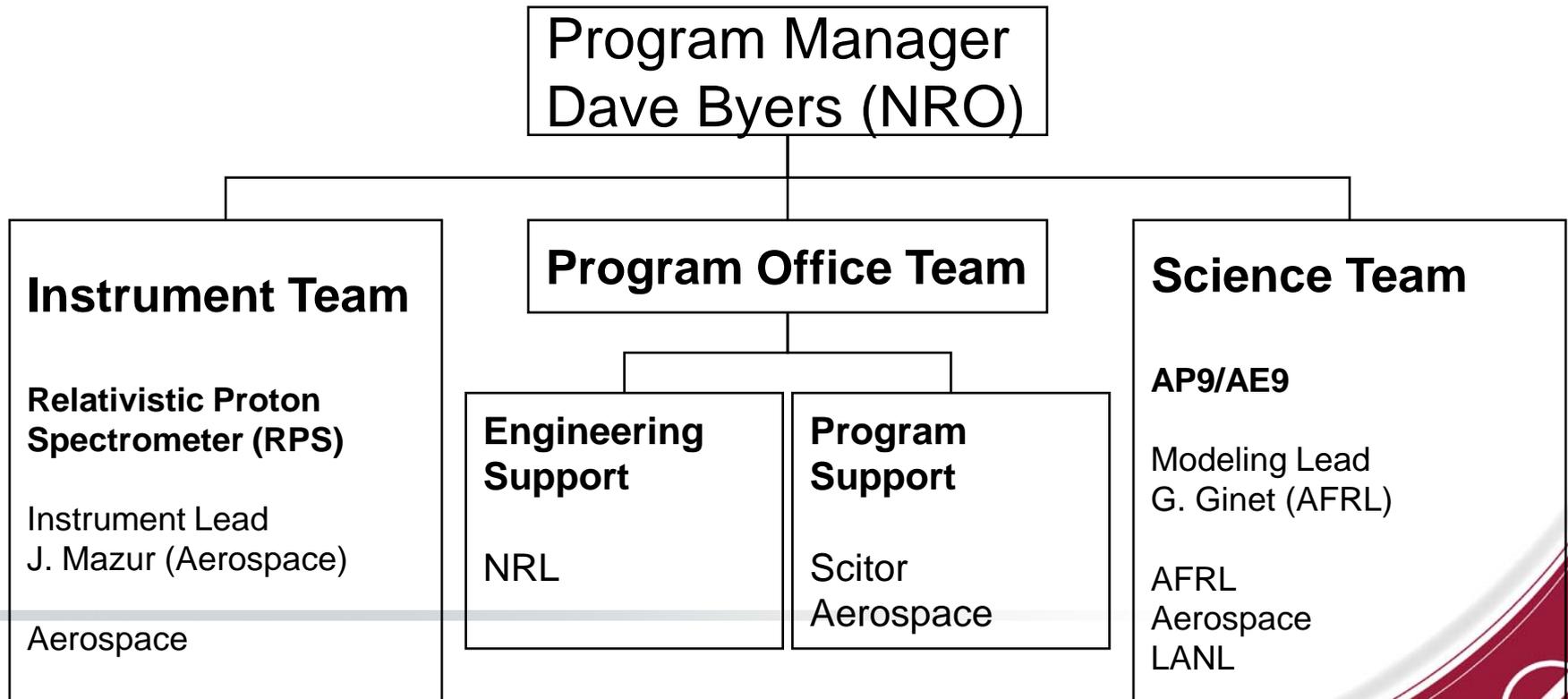
# Outline

- Project Overview
- Requirements Review
- Implementation Approach
- Status Update
- Future Plans
- Appendix - Impact of AE9/AP9 on the use of Environmental Effects Codes



# Proton Spectrometer Belt Research Program

- The objective of the PSBR program is to reduce uncertainty in the radiation environment specifications used to design satellites
- The PSBR program consists of two elements
  - *Aerospace's RPS sensor to fly on NASA's RBSP mission*
  - *The AE9/AP9 modeling effort*

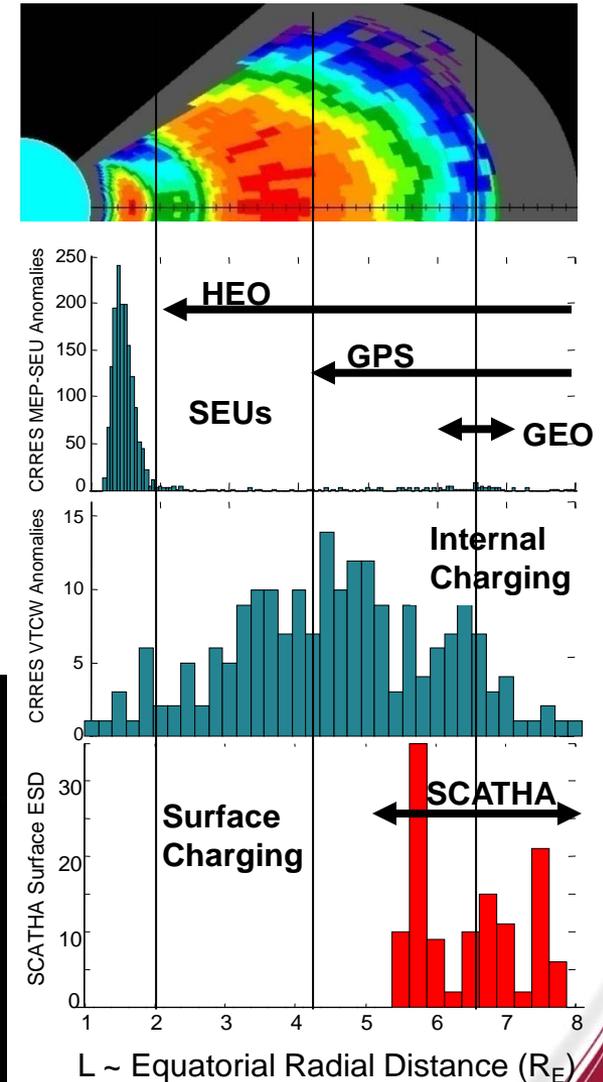
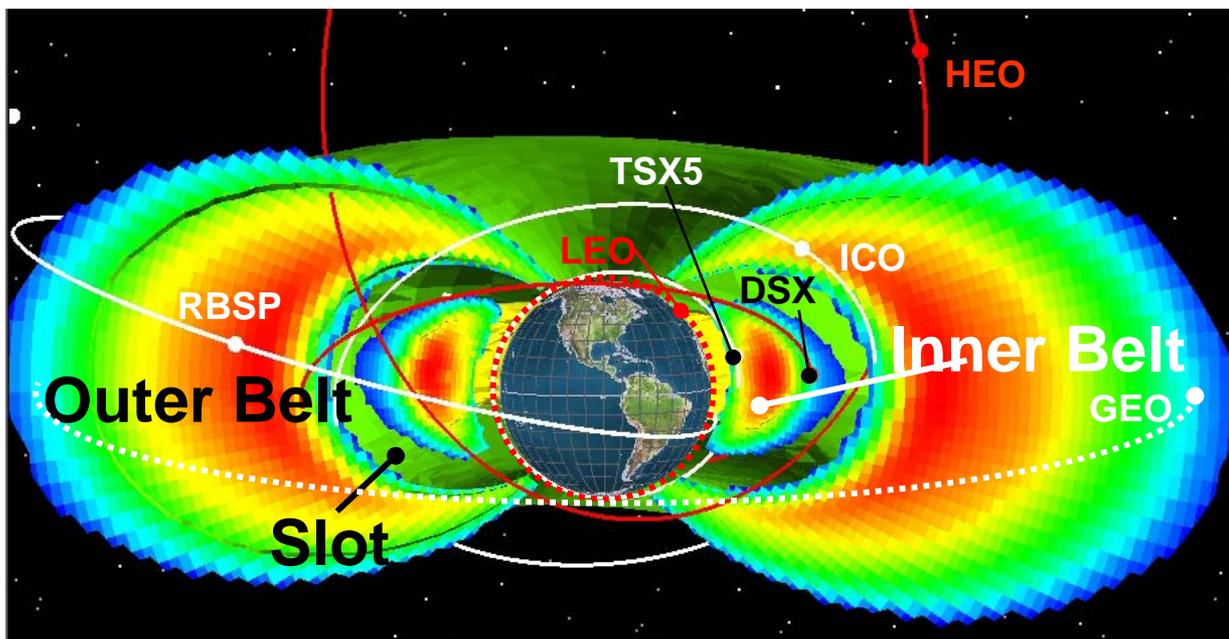


# AE9/AP9 Overview

OBJECTIVE: Provide satellite designers with a definitive model of the trapped energetic particle and plasma environment to include:

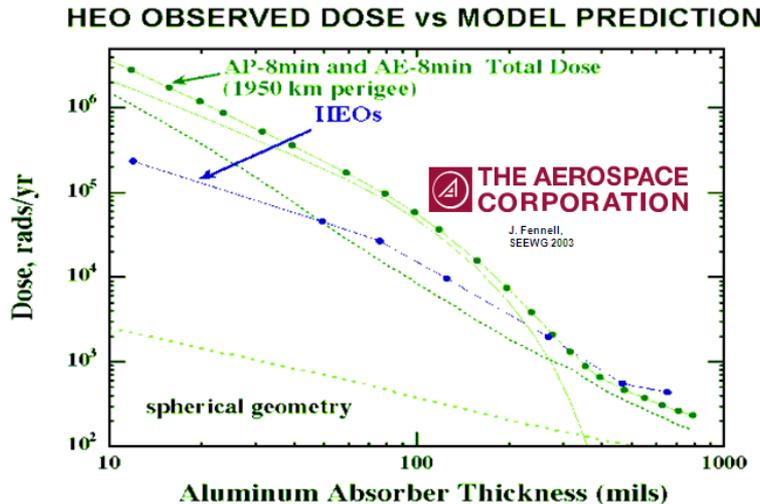
- Quantitative accuracy
- Indications of uncertainty
- Flux probability of occurrence and worst cases for different exposure periods
- Broad energy ranges including hot plasma & very energetic protons
- Complete spatial coverage

To achieve this objective, AE9/AP9 will have to be fundamentally different from and far more complex than AE8/AP8



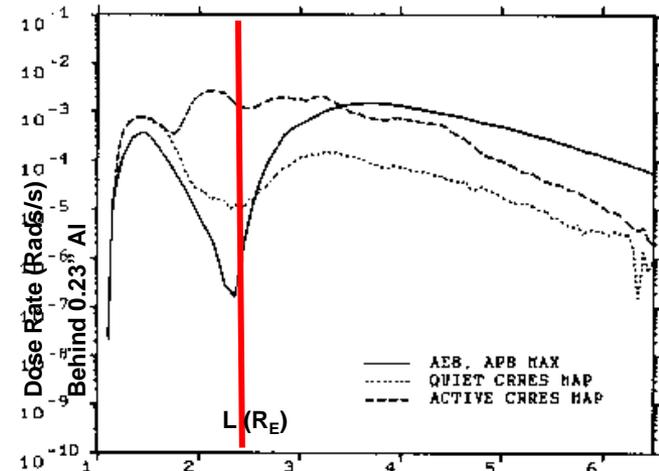
# Shortcomings of AE8/AP8

## Example: Highly Elliptic Orbit (HEO)



HEO dose measurements show that current radiation models (AE8 & AP8) **over estimate the dose** for thinner shielding

## Example: Medium-Earth Orbit (MEO)



For MEO orbit ( $L=2.2$ ), #years to reach 100 kRad:  
 Quiet conditions (NASA AP8, AE8) : 88 yrs  
 Active conditions (CRRES active) : 1.1 yrs  
 AE8 & AP8 **under estimate the dose** for 0.23" shielding

## THE AE8/AP8 models are inadequate:

- They are quantitatively wrong by different degrees depending on location, energy, and species
- They are incapable of accurately representing the risk associated with environmental dynamics
- They contain no indication of the uncertainty due to the limitations of the underlying measurements



# Requirements

Summary of SEEWG, NASA workshop & AE(P)-9 outreach efforts:

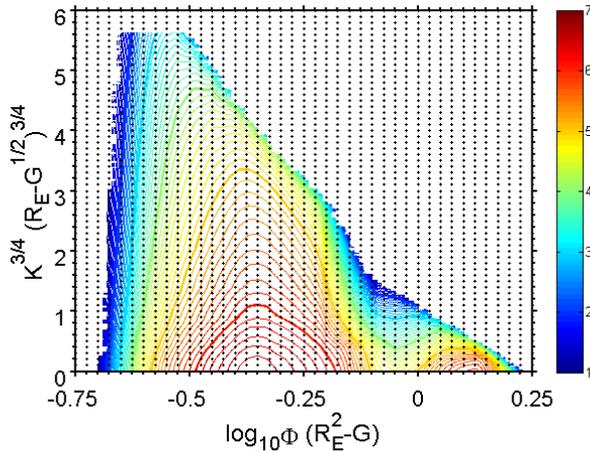
Priority	Species	Energy	Location	Time Variation	Effects
1	Protons	>10 MeV (> 80 MeV)	LEO & MEO	Mission statistics (i.e. % thresholds)	Dose, SEE, DD, nuclear activation
2	Electrons	> 1 MeV	LEO, MEO & GEO	5 min, 1 hr, 1 day, 1 week, & mission	Dose, internal charging
3	Plasma	30 eV – 100 keV (30 eV – 5 keV)	LEO, MEO & GEO	5 min, 1 hr, 1 day, 1 week, & mission	Surface charging & dose
4	Electrons	100 keV – 1 MeV	MEO & GEO	5 min, 1 hr, 1 day, 1 week, & mission	Internal charging, dose
5	Protons	1 MeV – 10 MeV (5 – 10 MeV)	LEO, MEO & GEO	Mission statistics	Dose (e.g. solar cells)

(indicates especially desired or deficient region of current models)



# AE9/AP9 Implementation

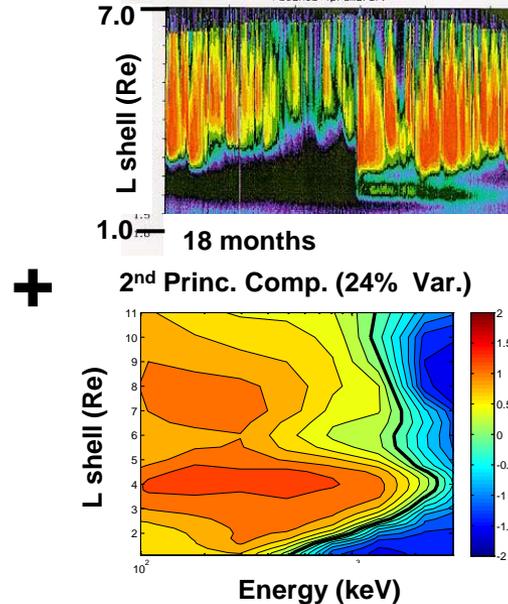
Satellite data



## Flux maps

- Median, 95<sup>th</sup> percentile of statistical distribution at each grid point
- Derived from empirical data
- Interpolation algorithms needed to fill in the gaps

Satellite data & physics-based models

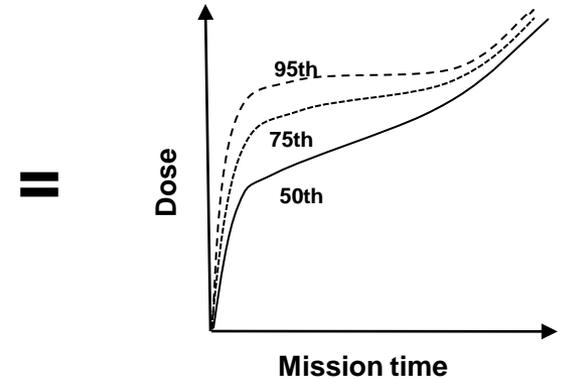


## Space/time covariance

Correlate data in space and time

- From data, if enough (electrons)
- From physics-based models when not enough (protons, plasma)
- Fixed sampling time scale (one day)

User's orbit & Monte-Carlo simulations



## User application

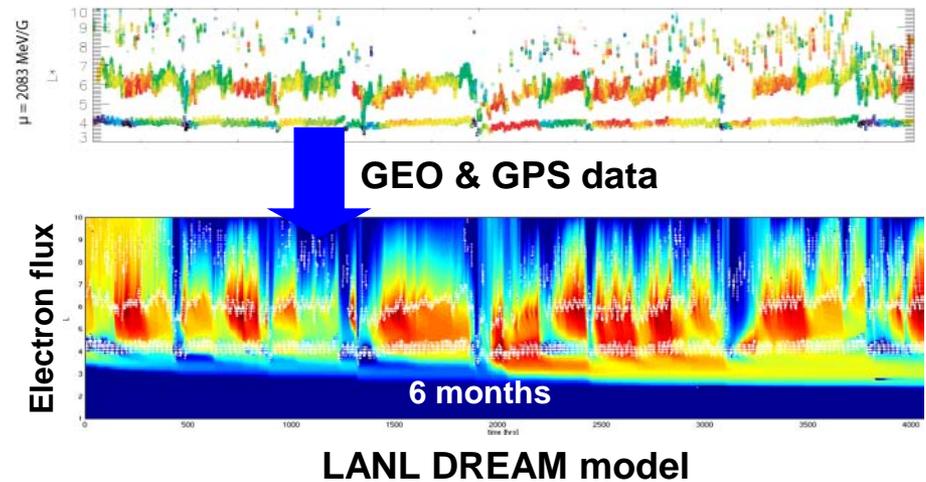
Flux vs time in “Standard Solar Cycle” or in Monte Carlo scenarios

Compute dose, SEE, charging etc in post-processing

Obtain median, 75<sup>th</sup>, 90<sup>th</sup> or other confidence levels



# Standard Solar Cycle



- The “Standard Solar Cycle” is an 11+ year “reanalysis”
- It combines data and numerical physics-based simulation via data assimilation for an entire solar cycle (or more)
- The Standard Solar Cycle is a real, past interval with real magnetic storms and, therefore, realistic time evolution
- Proposed missions can “fly through” the Standard Solar Cycle (by time shifting their launch date into the past)
- For long missions, the Standard Solar Cycle represents a single, highly realistic scenario
- However, it does not provide much in the way of error bars—all solar cycles are different



# Monte Carlo Scenarios

- The requirement to provide statistics (variously called uncertainty, error bars, or confidence intervals) leads to computing probability integrals in a high-dimensional space (easily  $>10^5$  variables)
- The only economical way to perform such an integral is to solve it via Monte Carlo methods
- The most straightforward way to implement the Monte Carlo integral is to generate “realistic” mission-length global radiation environment scenarios and “fly” the proposed mission through them
- The Monte Carlo problem is broken down into surrogate (multivariate) time series of a small number (10s) of “principal components” (PCs) of global variation.
- The time evolution is governed by spatiotemporal covariance of fluxes from observations or global simulations
- The time series of these PCs can be converted into a time series of flux at the spacecraft
- From the flux time series, one can compute expected effects (dose, charging, SEE)
- By computing effects for many scenarios, one can obtain confidence intervals on the severity of the effects
- One can then reasonably answer questions like “how much do I reduce my risk of failure if I double my shielding?”



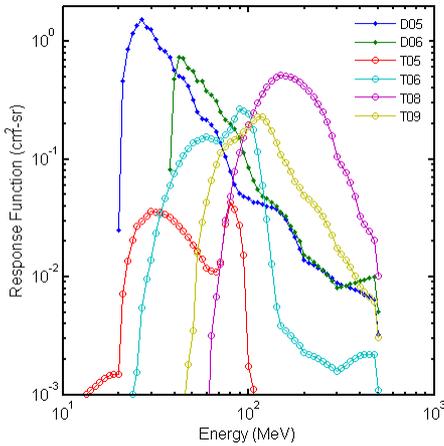
# Spectral/Angular Inversion

- To exploit certain symmetries in the particle population, the model requires unidirectional differential flux (e.g.,  $\#/cm^2/s/sr/MeV$ )
- We must determine the unidirectional differential flux at a given energy with a given local pitch angle (angle between particle momentum and magnetic field)
- With few exceptions, our long-term measurements have poor energy and angular resolution (i.e., most are omnidirectional integral fluxes)
- We have to make some assumptions and perform an inversion (a fit)
- We have developed a handful of ad hoc maximum likelihood algorithms that work “well enough”
- Once we have an acceptable global statistical model, we can use it in turn to improve our inversions for the next version of the model

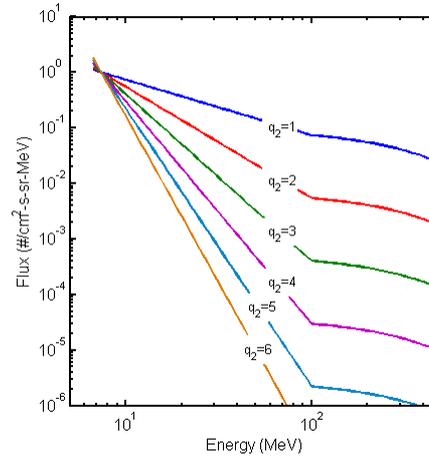


# Spectral Inversion Example

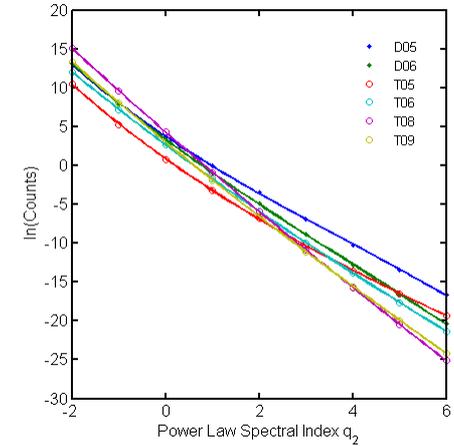
(1) Channel response functions



(2) Assume a spectral shape



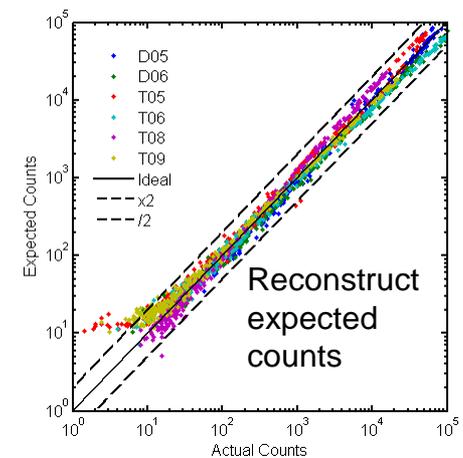
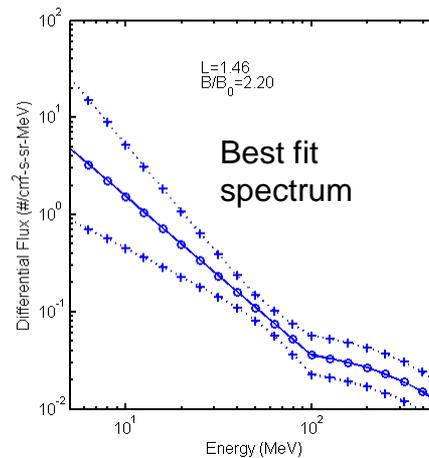
(3) Integrate (1) with (2) to obtain channel response to input spectrum



(4) Vector of Observed Counts

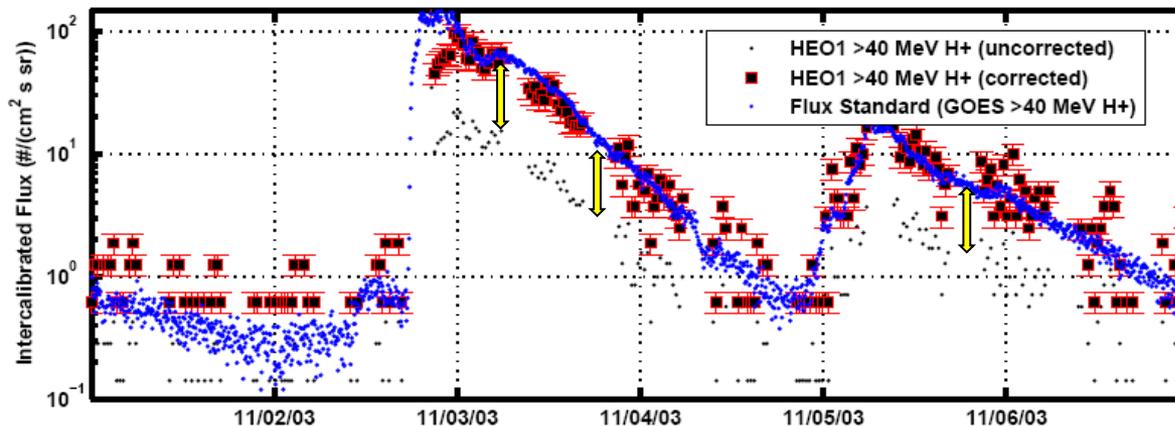
$$\begin{bmatrix} C_1 \\ C_2 \\ C_3 \\ C_4 \\ C_5 \\ C_6 \end{bmatrix}$$

Optimization routine finds "best"  $q_1$ ,  $q_2$  to fit observed counts

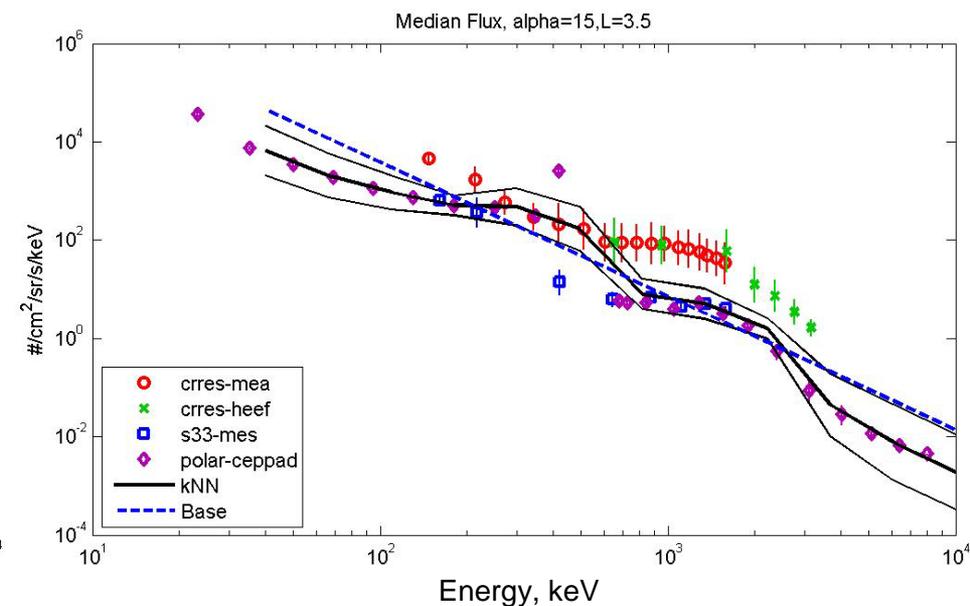
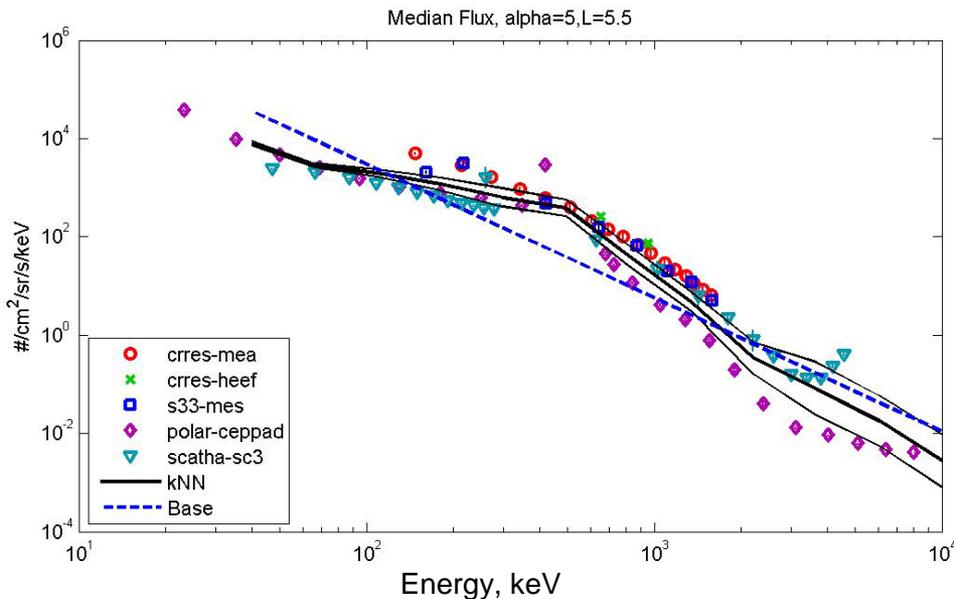


# Intercalibration

- Many of the measurements we employ were performed by “sensors of opportunity” that were designed and calibrated in keeping with their own mission objectives. Therefore, the pre-flight calibrations which we would find most useful usually were not performed
  - *Such calibrations were beyond the scope of these missions*
  - *We employ “on-orbit intercalibration” as a work-around*
  - *For Protons, the “gold standard” is GOES*
  - *For Electrons, it’s CRRES*
- The example below shows HEO-1 data corrected to match GOES during a solar particle event
- The calibration process estimates (and removes) the systematic error
- The correction process also estimates the size of the residual random error
- The residual error is propagated into the AE9/AP9 model



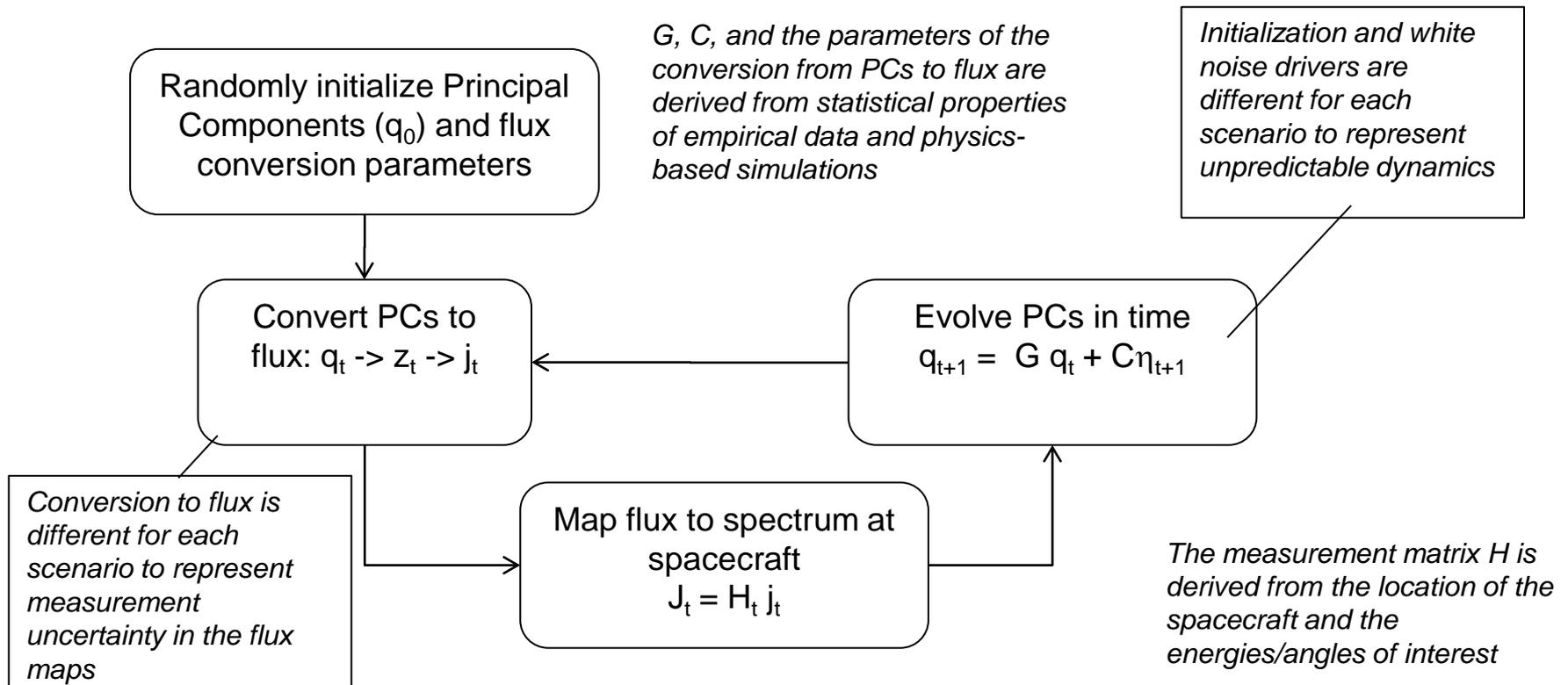
# Measurement error and Binning



- When data from different missions is binned together, sometimes it all agrees pretty well, sometimes it doesn't
- Polar tends to dominate the statistics because of its long duration
- We resolve the inconsistency using a nearest-neighbors interpolation onto a standard grid – we interpolate the *deviation* from a simple “base” model.
- We bootstrap that interpolation over different combinations of instruments to obtain an error estimate for the interpolated flux
- This error estimate is then used to generate the perturbations to the flux map for each Monte Carlo scenario



# Monte Carlo Architecture



- This flow chart represents a single scenario, which provides a flux spectrum time series at the spacecraft for the whole mission.
- To obtain percentiles and confidence intervals, one post-processes the flux time series and computes statistics *on the estimated radiation effects across scenarios.*



# A note on coordinates

- For compatibility with simulation codes, we'll use E/K/ $\Phi$  coordinates
- For the Monte Carlo scenarios, we use Olson-Pfizer Quiet (OPQ)
- For the standard solar cycle, we use whatever field model the reanalysis used
- Directly computing  $L^*$  or  $\Phi$  is too slow for use in a user application
  - *Our nominal worst case is a 10 year LEO mission that requires an  $L^*$  value every 10 seconds. This would take weeks using a traditional  $L^*$  algorithm*
  - *LANL developed a fast  $L^*$  neural network for a recent Tsyganenko model for GEO*
  - *We have developed a neural network for OPQ for the whole radiation belt*



# AE9/AP9 Status

- Spectral and angular inversion algorithms selected and implemented for AE9/AP9 beta release
- Fast “L\*” algorithms developed—final integration underway
- GPS, LANL-GEO, HEO, ICO, TSX-5 data nearly ready for ingest
- TEM-2 & TPM-2 Monte Carlo algorithms implemented in Matlab
  - *TEM-2 derived from: S3-3, SCATHA, CRRES, Polar*
  - *TPM-2 derived from: SIZM (Selesnick Inner Zone Model)*
  - *Improved data tables can be utilized without changes to code*
- Standard solar cycle
  - *Example electron standard solar cycles exist but have not been implemented as part of AE9/AP9 beta (TEM-2 Reanalysis, DREAM, Salamambo)*
  - *Proton standard solar cycle will be built from SIZM or Salamambo*

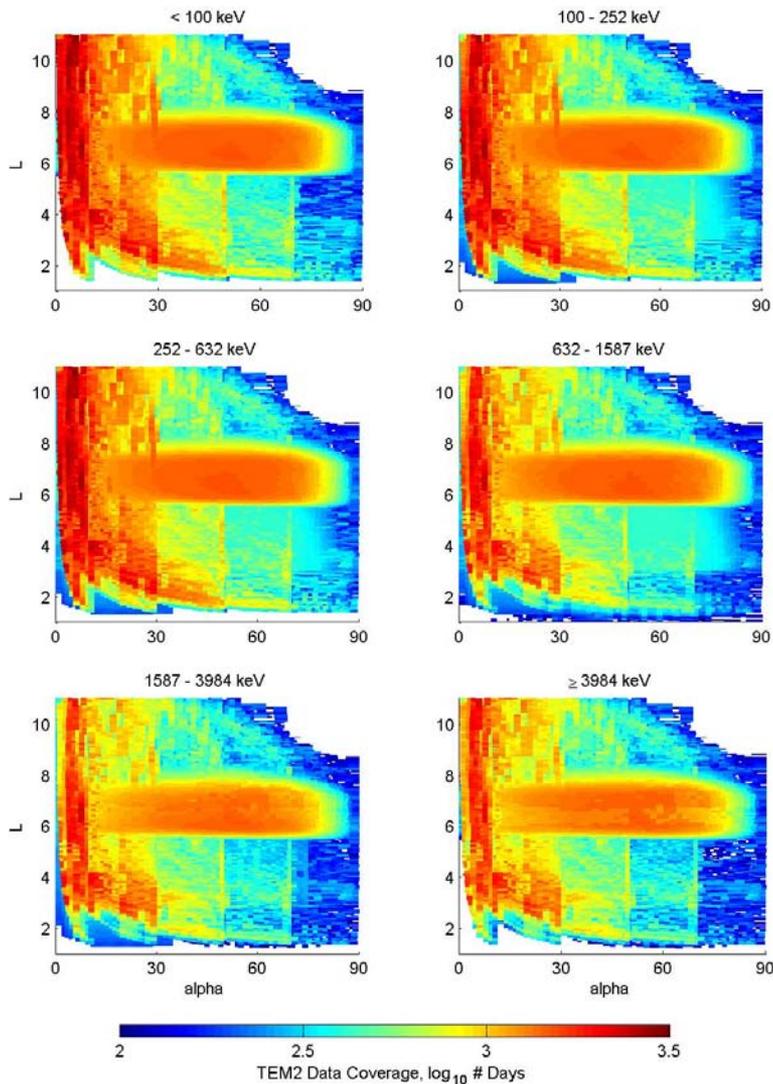


# Trapped Electron Model 2 Overview

- A statistical electron model (TEM-2c) was constructed from Polar, SCATHA, CRRES, and S3-3 data (TEM-2a had only CRRES and S3-3)
- Most statistical manipulations are not model-specific, so we can use the exact same “ngrs” code for AE9/AP9
- The model describes flux in  $E$ ,  $\alpha_{eq}$ ,  $L_m$  coordinates in the Olson-Pfitzer Quiet field model (AE9 will use  $E/K/\Phi$ )
- The model preserves:
  - *Statistical variation of flux at each grid point*
  - *Uncertainty in flux map (measurement error, sample size limitations)*
  - *Spatial covariance of flux (what’s a reasonable spectrum or L profile?)*
  - *Spatiotemporal covariance on 1 day timescale (how does the belt evolve?)*
- The model contains:
  - *50<sup>th</sup>, 95<sup>th</sup> percentile flux map on grid*
  - *Error & error covariance on flux map*
  - *Assumes Weibull distribution at each grid point*
  - *Spatial and spatio-temporal covariance:*
    - Retains 11 principal components of spatial variation
    - Matrices for multivariate, 1<sup>st</sup>-order autoregressive process on principal components



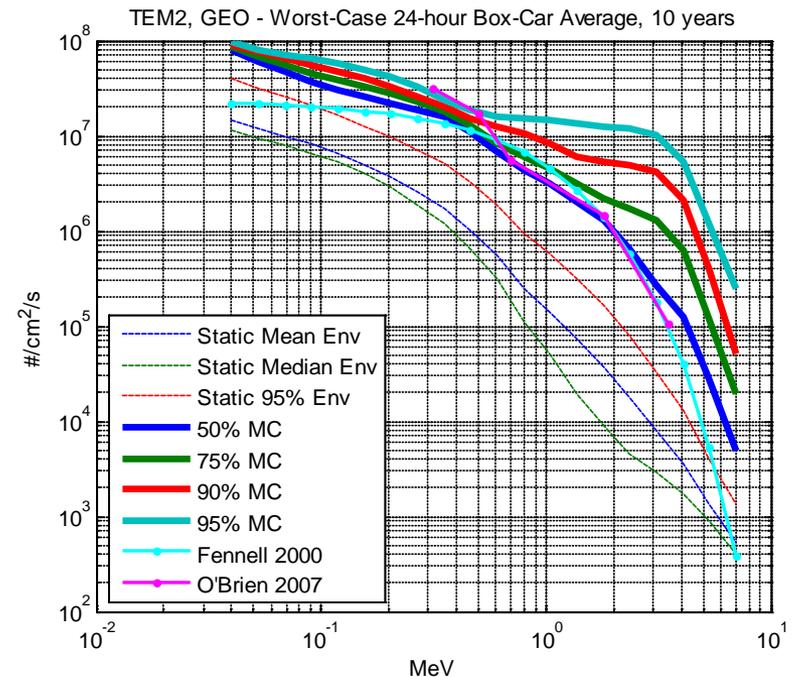
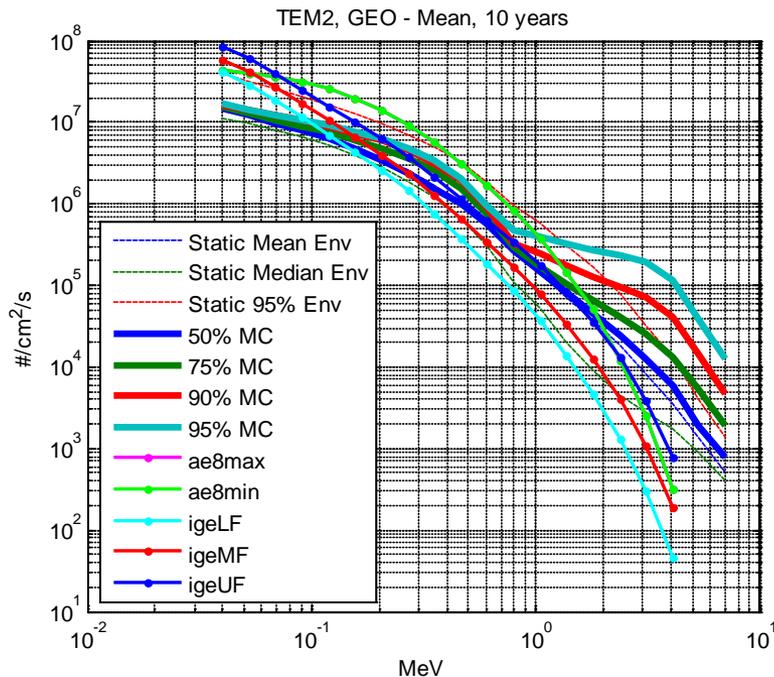
# TEM-2 Data Coverage



- TEM-2 combines S3-3, SCATHA, CRRES, and Polar data
- It has poor coverage at high equatorial pitch angle
- The wide horizontal band near L~7 is SCATHA data
- The vertical striations are an as-yet-resolved artifact in the Polar data
- Only the CRRES and S3-3 data have been quality controlled to remove regions of high background



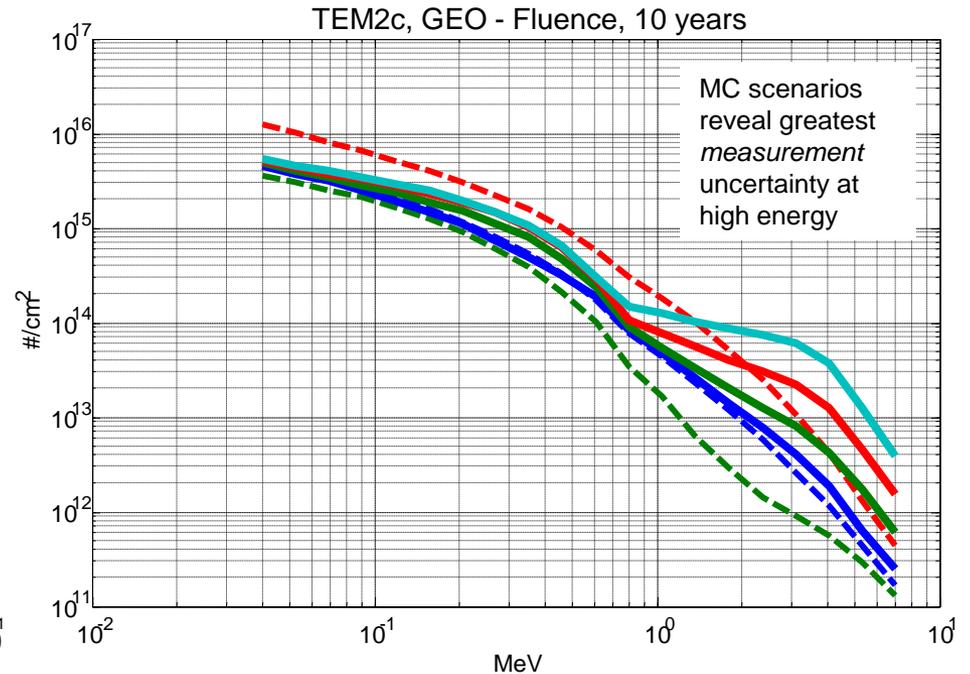
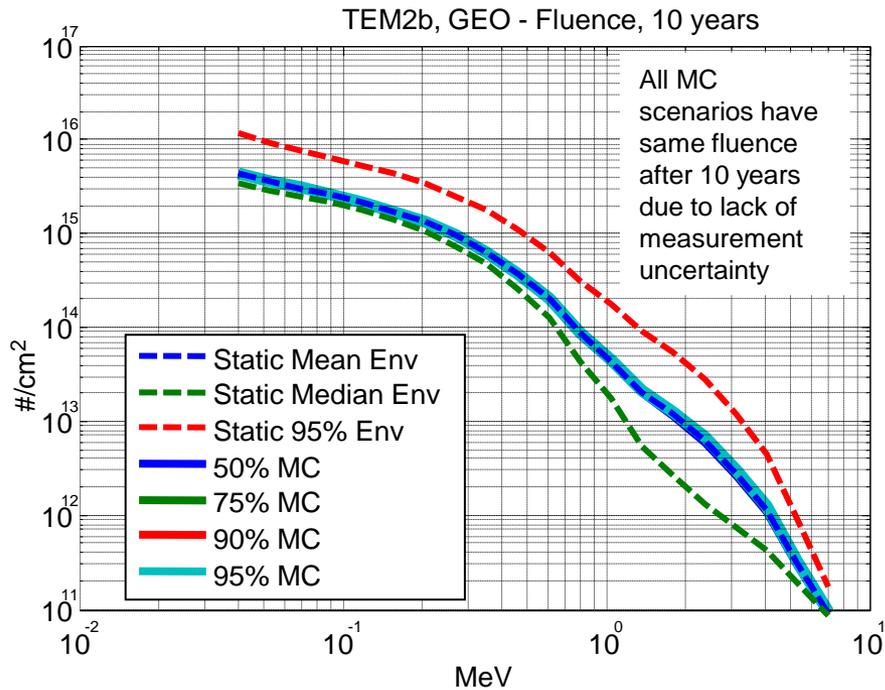
# TEM-2 Examples



- Below 100 keV, TEM-2 estimates lower mean fluxes than IGE (POLE) and AE8. Above 1 MeV, the reverse is true
- The median worst case for TEM-2 is comparable to O'Brien 2007. However, TEM-2 suggests that above 1 MeV, the measurement error has a very large impact on the worst case
- NOTE: No GEO data were used in the creation of TEM-2, so there's no reason (yet) to doubt the old specs



# A Note on “Measurement Error”



- When one improperly accounts for measurement error, all the Monte Carlo scenarios give the same fluence for long-term missions (E.g., TEM2b on left)
- The proper long-term mission fluence should have a spread due to underlying measurement error: incomplete calibration, insufficient statistics, unknown background (e.g., TEM2c on right)
- We achieve this in AE9/AP9 by perturbing the statistical flux map for each scenario—the perturbations are derived from an estimate of the measurement error.
- In AE9/AP9 even long scenarios (for which dynamics average out in the fluence) will still have a statistical spread due to uncertainty in the original measurements.



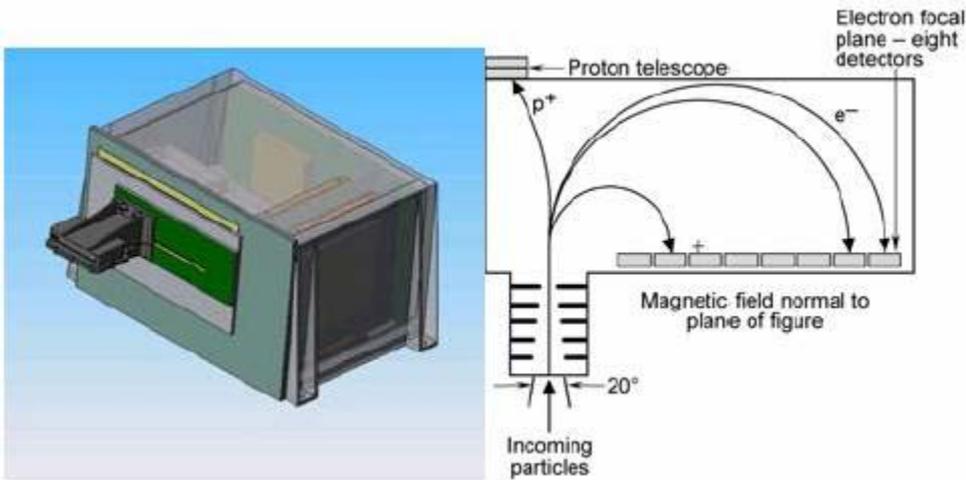
# Future Plans

- Beta release in early CY2010
  - *Improves on TEM-2 and TPM-2 with more data*
  - *New average plasma environment model (Polar GAMMICE/MICS)*
  - *TEM-2 converted to E/K/ $\Phi$  coordinates*
  - *Not certified for use in satellite design*
  - *Demonstrates Monte Carlo component to obtain feedback from engineers and scientists: Does this do what you need?*
- Version 1.0 release mid CY2011
  - *Ingest all remaining data*
  - *Improve intercalibration and background removal*
  - *Implement Standard Solar Cycle*
  - *Introduce “LEO” grid for improved accuracy at low altitude*
  - *Introduce “East-West” effect*
- Version 2.0 release ~1 year after RBSP launch
  - *Include RBSP, DSX, and TACSAT-4 data*
  - *Include ORBITALS and other international data if available*
  - *Continue to extend, expand Standard Solar Cycle*
  - *RBSP launch is scheduled for May 2012*
- RBSP is nominally a 2 year mission with a maximum life of 4 years



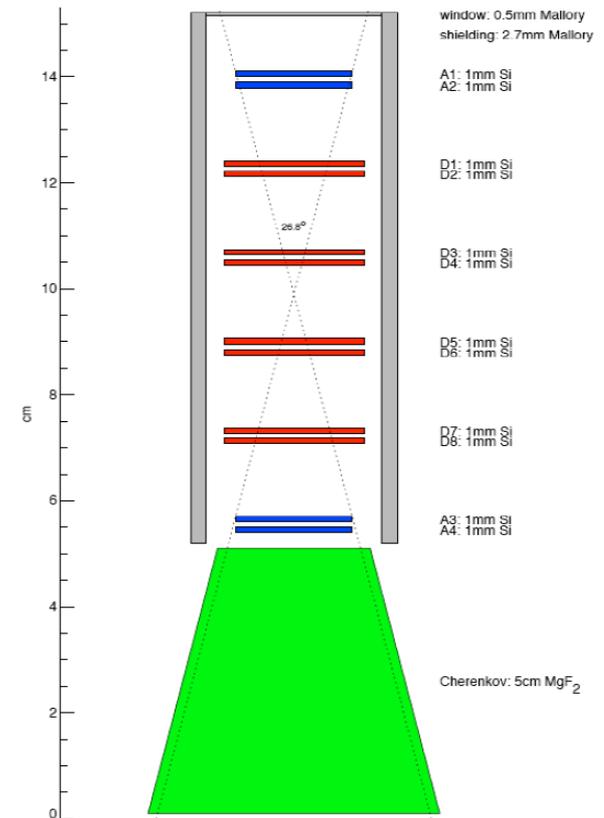
# Aerospace Sensors for NASA's RBSP Mission

## Magnetic Spectrometer: Relativistic Electrons

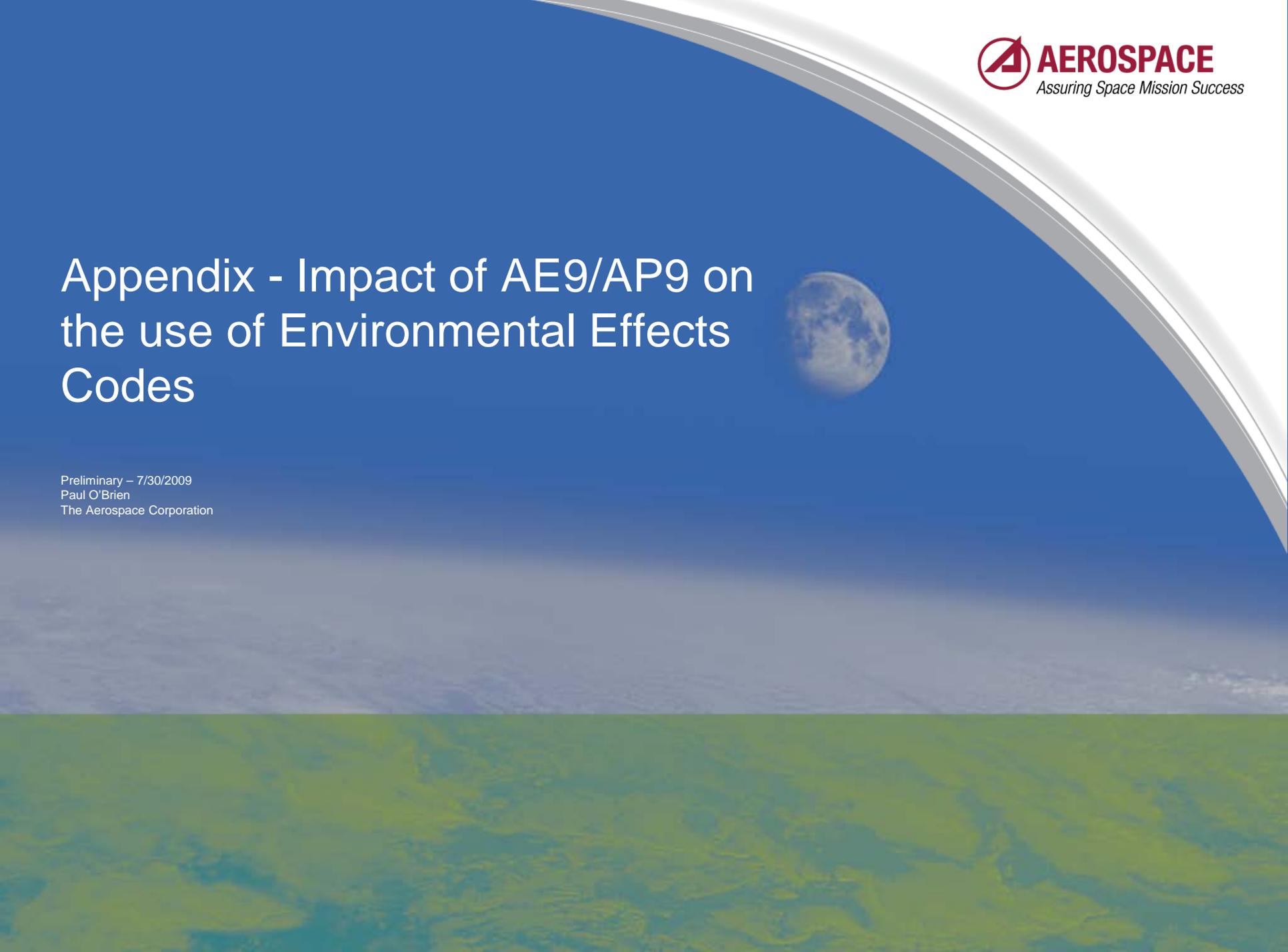


- NASA is funding development of MagEIS, which measures MeV electrons and ions (PI: Bern Blake)
- NRO is funding development of RPS, which measures 0.1-1 GeV protons (PI: Joe Mazur)

## Relativistic Proton Spectrometer



# Appendix - Impact of AE9/AP9 on the use of Environmental Effects Codes



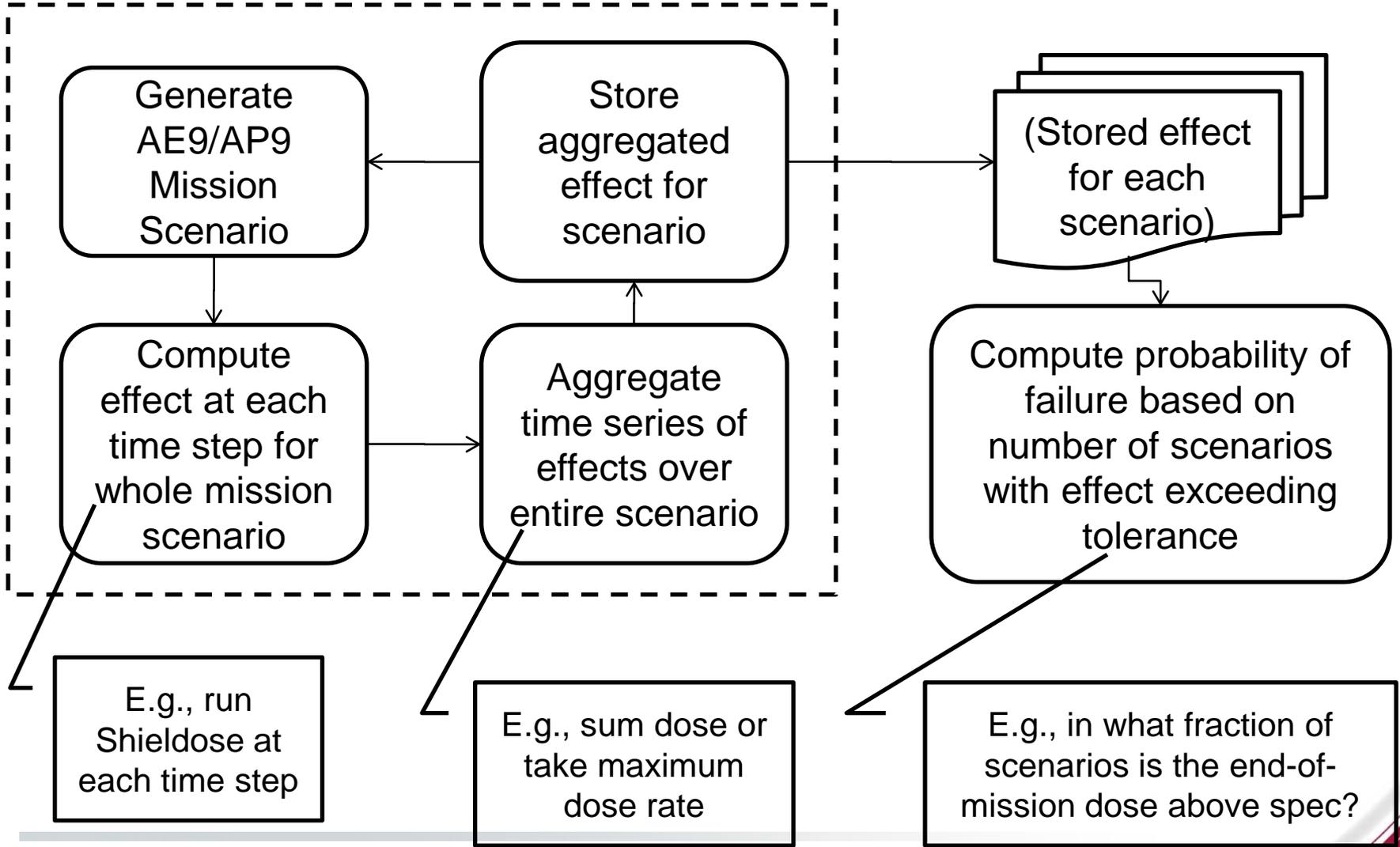
Preliminary – 7/30/2009  
Paul O'Brien  
The Aerospace Corporation

# Types of Linear Effects Calculations

- Most effects are linear functions of the environment
- There are three main types of linear effects
  - *Instantaneous rate effects (SEEs, surface charging)*
  - *Short-term accumulation effects (internal charging, annealing)*
  - *Whole-mission cumulative effects (total dose, displacement damage)*
- Effects codes available today essentially treat all of these effects as being derivable from a single, exact, static flux spectrum
  - *This is an effective, quick-and-dirty approach, and it will still be possible using AE9/AP9*
  - *However, it usually violates certain statistical principals such that it results in a “conservative” estimate with an unknown degree of margin*
  - *If one wants to understand the likelihood of failure, one must take a more sophisticated approach...*



# Effects Codes in the AE9/AP9 Environment



# Linear Effects in Equation Form

Instantaneous Rate Effect: Does  $y(t)$  exceed threshold  $y_0$  at any time during the scenario?

$$y(t) = \sum_s \int \sigma_s(E, \alpha, \beta) j_s(E, \alpha, \beta, t) dE d\alpha d\beta$$

Short-Term Accumulation Effect : Does  $y(t)$  exceed threshold  $y_0$  at any time during the scenario?

$$y(t) = \sum_s \int \sigma_s(E, \alpha, \beta) h(\tau) j_s(E, \alpha, \beta, t - \tau) dE d\alpha d\beta d\tau$$

Whole-Mission Cumulative Effect : Does  $y$  exceed threshold  $y_0$  at the end of the scenario?

$$y = \sum_s \int \sigma_s(E, \alpha, \beta) j_s(E, \alpha, \beta, t) dE d\alpha d\beta dt$$

$\sigma$  is a cross section that depends on species ( $s$ ), energy ( $E$ ), and angle ( $\alpha, \beta$ );  
 $h(\tau)$  is a moving average filter that represents a recovery process (e.g., charge bleed-off);  $j$  is particle flux from a scenario.

